Surfaces: outline

- 1. Regular surfaces
- 2. Parameterization of regular surfaces
- 3. Intrinsic properties (first fundamental form, Gaussian curvature, geodesic curvature, etc.)
- 4. The Gauss-Bonnet theorem
- 5. Example: intrinsically curved folds in liquid crystal elastomers



Figure 1: Gaussian curvature generation in liquid crystal elastomer sheets

Mechanics of Surfaces: outline

- 1. Kirchhoff's plate/membrane theory (rational treatment)
- 2. Bending energy of a developable surface (Wunderlich functional)
- 3. Example: curved fold origami



Figure 2: Two curved fold origami. The crease of the left one has non-zero torsion, which the right one has zero torsion.

 \mathcal{O} 1. Regular surfaces Def 1: A subset SCIR3 is a regular surface if for bp6S, I a neighborhood V in 123 and a map Z: U-> VILS of an open set UCIR onto VNSCIR³ s.t. D I is differentiable. $\vec{X}(u,v) = (X(u,v), Y(u,v), Z(u,v)), (U,v) \in U$ the functions X(U,V), Y(U,V), Z(U,V) have continuous partial derivatives Q Z is a homeomorphism: bijection, continuous, continuous inverse. 3 The regularity condition for V &GU, the differential dXq: 1R2-> R3 is one-tu-one. 2 U (u,v)(x(u,v), y(u,v), 4 Z(U,V) U Regularity condition: $\vec{\chi}_{\mu}(u_0, v_0) = \frac{\partial \vec{\chi}}{\partial u}(u_0, v_0)$, $\vec{\chi}_{\nu}(u_0, v_0) = \frac{\partial \vec{\chi}}{\partial v}(u_0, v_0)$ (2) Ju × Ju (U0, V) ≠0 daolen

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=) CUS20 5120 + SIM40 COS24 + SIM40 SIM24 = SIM20 = 0 Proposition 2: (change of parameters) S is a regular surface. $p \in S$. neighborhoods V_1, V_2 , $S \stackrel{\sim}{\downarrow} : U_1 \rightarrow V_1 \Pi S$. $I \stackrel{\sim}{\downarrow} : U_2 \rightarrow V_2 \Pi S$. $p \in \tilde{X}_1(U_1) \cap \tilde{X}_2(U_2) = W$ Then the change of coordinates $h = \overline{x_1}^2 \cdot \overline{x_2} : \overline{x_2}^2(w) \to \overline{x_1}^2(w)$ is a diffeo morphism. 同胚 XT(W) \mathcal{V} KI -) > M ズ(し) 大(し) v_{2} U2 x2"(w) X2 42 (PAL) $\overline{\mathcal{X}}_{I} = (\mathcal{X}_{I}(\mathcal{U}_{1},\mathcal{U}_{1}), \mathcal{Y}_{I}(\mathcal{U}_{2},\mathcal{U}_{1}), \mathcal{Z}_{I}(\mathcal{U}_{1},\mathcal{U}_{1}))$ proof The= (T2(U2, V2), J2(U2, V2), Z2(U2, V2)) $\frac{\partial(x_1,y_1)}{\partial(u_1v_1)}$ = $\psi = f(x_1,y_1), \quad (u_2 = g(x_1,y_1))$ regularity $f(x_1(u_1,u_1), y_1(u_1,u_1)) = U_1, f(x_1(u_1,u_1), y_1(u_1,u_1)) = U_1$ =) $U_1 = f(\pi_2(u_2,v_2), y_2(u_2,v_3)), U_1 = g(\pi_2(u_2,v_3), y_2(u_2,v_2))$ daolen®

(4) $\frac{\partial(\mathcal{U}_{1},\mathcal{V}_{1})}{\partial(\mathcal{U}_{2},\mathcal{V}_{2})} = \frac{\partial(f,g)}{\partial(\mathcal{I}_{2},\mathcal{Y}_{2})} \frac{\partial(\mathcal{I}_{2},\mathcal{Y}_{2})}{\partial(\mathcal{U}_{2},\mathcal{V}_{2})} = \frac{\partial(\mathcal{I}_{2},\mathcal{Y}_{2})}{\partial(\mathcal{U}_{2},\mathcal{V}_{2})} \left(\frac{\partial(\mathcal{I}_{1},\mathcal{Y}_{1})}{\partial(\mathcal{U}_{1},\mathcal{V}_{1})}\right)^{-} \neq 0$ $(do (armo)) = (\chi(u, v), g(u, v), z(u, v) + t)$ F- exists IL => h = Flox is differentiable. Example 2: Cylindrical surface $\vec{\chi} = \vec{\chi}(u, v) = (a \cos u, a \sin u, bv)$ Example 3: Ruled surface $\vec{x} = \vec{z}(u, v) = \vec{\alpha}(u) + v \vec{\lambda}(u)$ $\widetilde{X}_{\mu}(u,v) = \widetilde{a}(u) + \mu \mathscr{L}(u)$ $\widetilde{x}_{\nu}(u,v) = \widetilde{\varrho}(u)$ regularity: $\overline{\lambda}_{u} \times \overline{\lambda}_{v} = (\overline{a}'_{u1} + \nu l'_{u}) \times \overline{l}_{uv} \neq 0$ ()(U) · Cylindrical surface is a ruled surface aly) daollen

(5) 2. The tangent plane and normal Given a gregular surface $\vec{\chi} = \vec{\chi}(u, v)$ and a differentiable Curve U = U(t), U = V(t)⇒ r((l(t1, v(t)) in 123 VA $d\vec{\chi}(u(t), v(t))$ $= \overline{\chi_{u}} \frac{du(t)}{dt} + \overline{\chi_{v}} \frac{dv(t)}{dt} + \frac{1}{z_{v}} \frac{dv(t)}{dt$ $\int U(H) = U_0 + \alpha t = \frac{d\vec{k}(UH), U(H)}{dt} = \alpha \vec{\lambda}_u + b\vec{\lambda}_v$ Lu×Iv ≠0. > Tangent space tTB A TpS. Tangent plane : $\overline{X}(\lambda,\mu) = \overline{\chi}(\mu,\nu) + \overline{\chi}_{\mu}(\mu,\nu) + \mu \overline{\chi}_{\nu}(\mu,\nu)$ Normal 法向量 $\Pi(U,v) = \frac{\overline{\chi}_u(u,v) \times \overline{\chi}_v(u,v)}{|\overline{\chi}_u(u,v) \times \overline{\chi}_v(u,v)|}$ {Iu(U,U), Iv(U,U), Ti(U,U)}自然标架 natural coordinates daolen®

3. Parameterization of Kgubar Surfaces
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(U.v) E(V,
$$\overline{\chi}: U \rightarrow R^{3}$$

 $\overline{\chi}(U,v)$
(Displicit parameterization
 $f(x,y,z)$ ($\frac{2f}{2\pi}, \frac{2f}{2y}, \frac{2f}{2y} \neq 0$
 $f(x,y,z)$ ($\frac{2f}{2\pi}, \frac{2f}{2y}, \frac{2f}{2y} \neq 0$
 $f(x,y,z) = C \sim regular surface
implicit function them
Assume $\frac{2f}{2} \neq 0 \Rightarrow 2 = g(x,y) \Rightarrow f(x,y, g(x,y)) = C$
 $\Rightarrow \overline{\chi}(x,y) = (\chi, y, g(x,y))$
($\frac{2f}{2\pi}, \frac{2f}{2y}, \frac{2f}{2z}$) is the normal
Example 4: $\frac{\chi}{2-\chi} + \frac{2r}{2-\chi} = 1$ $\lambda e(-\infty, c)$ that $\lambda = 1$
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Date · $I = d \vec{x} (u, v) \cdot d \vec{x} (u, v)$ = $E(U,v)(du)^{2} + 2F(U,v)dudv + G(U,v)(dv)^{2}$ = (du, dv) (E F) (du)(F G) (dv)~ First Fundamental form Thm 2: The first fundamental form is independent of the choices of para regular parameterization. proof ; PA $\mathcal{U} = \mathcal{U}(\mathcal{U}, \mathcal{D}), \mathcal{U} = \mathcal{U}(\mathcal{U}, \mathcal{D})$ $\vec{\chi} = \vec{\chi} (\vec{u}, \vec{v}) = \vec{\chi} (u(\vec{u}, \vec{v}), \upsilon(\vec{u}, \vec{v}))$ $d\vec{\chi} = \vec{\chi}_{\vec{v}}(\vec{u},\vec{v})d\vec{u} + \vec{\chi}_{\vec{v}}(\vec{u},\vec{v})d\vec{v}$ $= \left(d\hat{u}, d\hat{z} \right) \begin{pmatrix} \tilde{E} & \tilde{F} \\ \hat{F} & \tilde{G} \end{pmatrix} \begin{pmatrix} d\tilde{v} \\ d\hat{v} \end{pmatrix} = \left(du, dv \right) \begin{pmatrix} E & F \\ F & G \end{pmatrix} \begin{pmatrix} du \\ dv \end{pmatrix}$