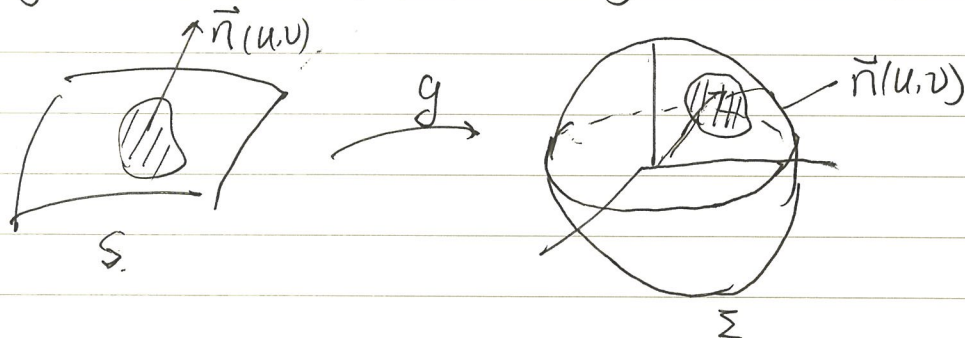


How to determine k_1, k_2, ρ_0 for arbitrary coordinates?

(10) The Gauss map and Weingarten map

$\vec{r} = \vec{r}(u, v)$. \sim regular surface

$g: (\vec{r}(u, v)) = \vec{n}(u, v)$, $g: S \rightarrow \Sigma$ Gauss map



$g_*: T_p S \rightarrow T_{g(p)} \Sigma$

Let $u = u(t)$, $v = v(t)$

$g(\vec{r}(u(t), v(t))) = \vec{n}(u(t), v(t))$

$$\Rightarrow g_* \left(\frac{d\vec{r}}{dt} \right) = g_* \left(\vec{r}_u \frac{du}{dt} + \vec{r}_v \frac{dv}{dt} \right) = \vec{n}_u \frac{du}{dt} + \vec{n}_v \frac{dv}{dt}$$

$$\Rightarrow g_*(\vec{r}_u) = \vec{n}_u, \quad g_*(\vec{r}_v) = \vec{n}_v$$

$W = -g_*: T_p S \rightarrow T_p S \sim$ Weingarten map

Thm 10.1. $\text{II} = W(d\vec{r}) \cdot d\vec{r}$

proof: $d\vec{r} = \vec{r}_u du + \vec{r}_v dv$

$$\begin{aligned} W(d\vec{r}) &= -g_*(\vec{r}_u) du - g_*(\vec{r}_v) dv \\ &= -(\vec{n}_u du + \vec{n}_v dv) = -d\vec{n} \end{aligned}$$

$$\Rightarrow \text{II} = W(d\vec{r}) \cdot d\vec{r}$$

Thm 10.2. $W(d\vec{r}) \cdot \delta\vec{r} = d\vec{r} \cdot W(\delta\vec{r})$

proof: $d\vec{r} = \vec{r}_u du + \vec{r}_v dv$, $\delta\vec{r} = \vec{r}_u \delta u + \vec{r}_v \delta v$

$$W(d\vec{r}) = -(\vec{n}_u du + \vec{n}_v dv), \quad W(\delta\vec{r}) = -(\vec{n}_u \delta u + \vec{n}_v \delta v)$$

$$W(d\vec{r}) \cdot \delta\vec{r} = -(\vec{n}_u du + \vec{n}_v dv) \cdot (\vec{r}_u \delta u + \vec{r}_v \delta v)$$

$$= -(\vec{r}_u du + \vec{r}_v dv) \cdot (\vec{n}_u \delta u + \vec{n}_v \delta v) = d\vec{r} \cdot W(\delta\vec{r})$$

Let λ and $d\vec{r}$ be the eigenvalue and eigenvector of W

$$\text{i.e. } W(d\vec{r}) = \lambda d\vec{r}$$

$$\text{Then } k_n = \frac{\text{II}}{\text{I}} = \frac{W(d\vec{r}) \cdot d\vec{r}}{d\vec{r} \cdot d\vec{r}} = \lambda \quad \text{self-conjugate}$$

Proposition: If a linear transformation A satisfies $A(\vec{u}) \cdot \vec{v} = \vec{u} \cdot A(\vec{v})$

Then ① The eigenvalues of A are real.

$$A(\vec{v}) \cdot \vec{v} = \lambda v \cdot \vec{v} = v \cdot A(\vec{v}) = \bar{\lambda} v \cdot \vec{v}$$

$$\Rightarrow (\bar{\lambda} - \lambda) v \cdot \vec{v} = 0 \quad \Rightarrow \bar{\lambda} = \lambda$$

② if λ_1, λ_2 are two eigenvalues of A , $\lambda_1 \neq \lambda_2$ and the corresponding eigenvectors are v_1, v_2 , Then $v_1 \cdot v_2 = 0$

$$\text{proof: } A(v_1) = \lambda_1 v_1, \quad A(v_2) = \lambda_2 v_2$$

$$A(v_1) \cdot v_2 = v_1 \cdot A(v_2) \Rightarrow \lambda_1 v_1 \cdot v_2 = \lambda_2 v_1 \cdot v_2$$

$$\Rightarrow (\lambda_1 - \lambda_2) v_1 \cdot v_2 = 0 \Rightarrow v_1 \cdot v_2 = 0$$

Thm 10.3. The two eigenvalues of the Weingarten map are the two principal curvatures, and the corresponding eigenvectors are the two principal tangents

$$\text{proof: Let } W(e_1) = \lambda_1 e_1, \quad W(e_2) = \lambda_2 e_2$$

$$\forall e = \cos\theta e_1 + \sin\theta e_2$$

$$W(e) = \cos\theta W(e_1) + \sin\theta W(e_2) = \lambda_1 \cos\theta e_1 + \lambda_2 \sin\theta e_2$$

$$\begin{aligned} \Rightarrow k(\theta) &= \frac{W(e) \cdot e}{e \cdot e} = (\lambda_1 \cos\theta e_1 + \lambda_2 \sin\theta e_2) \cdot (\cos\theta e_1 + \sin\theta e_2) \\ &= \lambda_2 + (\lambda_1 - \lambda_2) \cos^2\theta \end{aligned}$$

$$\Rightarrow \begin{cases} \theta = 0, & k_n(\theta) = \lambda_2 \\ \theta = \frac{\pi}{2}, & k_n(\theta) = \lambda_1 \end{cases}$$

Computation of principal curvatures and principal directions.

$S: \vec{r} = \vec{r}(u, v)$, $\delta \vec{r} = \vec{r}_u \delta u + \vec{r}_v \delta v$ is a principal direction at (u, v)

$$\Rightarrow W(\delta \vec{r}) = \lambda \delta \vec{r}$$

$$\Rightarrow -(\vec{n}_u \delta u + \vec{n}_v \delta v) = \lambda(\vec{r}_u \delta u + \vec{r}_v \delta v)$$

$$\begin{aligned} \cdot \vec{r}_u &\Rightarrow \begin{cases} L \delta u + M \delta v = \lambda(E \delta u + F \delta v) \\ M \delta u + N \delta v = \lambda(F \delta u + G \delta v) \end{cases} \\ \cdot \vec{r}_v & \end{aligned}$$

$\therefore (\delta u, \delta v)$ is a ^{nonzero} solution to $\begin{cases} (L - \lambda E) \delta u + (M - \lambda F) \delta v = 0 \\ (M - \lambda F) \delta u + (N - \lambda G) \delta v = 0 \end{cases}$

$$\Rightarrow \begin{vmatrix} L - \lambda E & M - \lambda F \\ M - \lambda F & N - \lambda G \end{vmatrix} = 0$$

$$\Rightarrow \lambda^2 (EG - F^2) - \lambda (LG - 2MF + NE) + (LN - M^2) = 0$$

$$\Rightarrow K_1 + K_2 = 2H = \frac{LG - 2MF + NE}{EG - F^2} \quad \sim \text{平均曲率 } H$$

$$K_1 K_2 = K = \frac{LN - M^2}{EG - F^2} \quad \sim \text{Gauss Curvature}$$

$$\Rightarrow K_1 = H + \sqrt{H^2 - K}, \quad K_2 = H - \sqrt{H^2 - K} \quad \star$$

⊕ Fundamental theorem of surfaces

⊙ Natural coordinates

Regular surfaces $\vec{r} = \vec{r}(u, v)$

natural coordinates:

$$\{\vec{r}_u, \vec{r}_v, \vec{n}\} \quad \vec{n} = \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|}$$

$$\vec{r} = \vec{r}(u^1, u^2) \quad \vec{r}_\alpha = \frac{\partial \vec{r}(u^1, u^2)}{\partial u^\alpha}, \quad \alpha = 1, 2.$$

$$d\vec{r} = \vec{r}_\alpha(u^1, u^2) du^\alpha \quad \sim \text{Einstein notation.}$$

First fundamental form: $g_{\alpha\beta} = \vec{r}_\alpha \cdot \vec{r}_\beta$

Second fundamental form: $b_{\alpha\beta} = \vec{r}_{\alpha\beta} \cdot \vec{n} = -\vec{r}_\alpha \cdot \vec{n}_\beta = -\vec{r}_\beta \cdot \vec{n}_\alpha$

Then the two fundamental forms can be written as

$$I = g_{\alpha\beta} du^\alpha du^\beta$$

$$II = b_{\alpha\beta} du^\alpha du^\beta$$

Recall that $g_{\alpha\beta}$ is positive definite \Rightarrow inverse $g^{\alpha\beta}$ s.t.
 $g^{\alpha\beta} g_{\beta\gamma} = \delta^\alpha_\gamma$

natural coordinates: $\frac{\partial \vec{r}}{\partial u^\alpha} = \vec{r}_\alpha$

$$\Rightarrow \begin{cases} \frac{\partial \vec{r}_\alpha}{\partial u^\beta} = T_{\alpha\beta}^\gamma \vec{r}_\gamma + C_{\alpha\beta} \vec{n} \\ \frac{\partial \vec{n}}{\partial u^\beta} = D_\beta^\gamma \vec{r}_\gamma + D_\beta \vec{n} \end{cases}$$

How to determine

$$T_{\alpha\beta}^\gamma \quad C_{\alpha\beta} \quad D_\beta^\gamma \quad D_\beta ?$$

from $\vec{r}(u^1, u^2), \vec{n}$

$$\bullet \quad C_{\alpha\beta} = \frac{\partial \vec{r}_\alpha}{\partial u^\beta} \cdot \vec{n} = \vec{r}_{\alpha\beta} \cdot \vec{n} = b_{\alpha\beta}$$

$$\bullet \quad \frac{\partial \vec{n}}{\partial u^\beta} \cdot \vec{r}_\gamma = D_\beta^\gamma \vec{r}_\gamma \cdot \vec{r}_\gamma = D_\beta^\gamma g_{\gamma\epsilon} \Rightarrow D_\beta^\gamma g_{\gamma\epsilon} = -b_{\beta\epsilon}$$

$$D_\beta^\gamma = -b_{\beta\epsilon} g^{\epsilon\gamma}$$

Let $b_{\beta}^{\alpha} = b_{\beta\gamma}^{\alpha} g^{\gamma\epsilon}$ $\sim g^{\epsilon\alpha} g_{\epsilon\beta}$. 指标 $\uparrow \downarrow$

for example: $b_{\beta}^{\alpha} g_{\alpha\eta} = b_{\beta\gamma}^{\alpha} g^{\gamma\epsilon} g_{\epsilon\eta} = b_{\beta\gamma}^{\alpha} \delta_{\eta}^{\gamma} = b_{\beta\eta}^{\alpha}$

$$\boxed{D_{\beta}^{\alpha} = -b_{\beta}^{\alpha}}$$

$$|\vec{n}|=1 \Rightarrow \frac{\partial \vec{n}}{\partial u^{\beta}} \perp \vec{n}$$

$$\Rightarrow \begin{cases} \frac{\partial \vec{r}_{\alpha}}{\partial u^{\beta}} = \Gamma_{\alpha\beta}^{\gamma} \vec{r}_{\gamma} + b_{\alpha\beta}^{\gamma} \vec{n} \\ \frac{\partial \vec{n}}{\partial u^{\beta}} = -b_{\beta}^{\alpha} \vec{r}_{\alpha} \end{cases}$$

How about $\Gamma_{\alpha\beta}^{\gamma}$?

$$\vec{r}_{\alpha\beta} \cdot \vec{r}_{\epsilon} = \Gamma_{\alpha\beta}^{\gamma} \vec{r}_{\gamma} \cdot \vec{r}_{\epsilon} = \Gamma_{\alpha\beta}^{\gamma} g_{\gamma\epsilon}$$

Let $\Gamma_{\alpha\beta}^{\gamma} g_{\gamma\epsilon} = \Gamma_{\epsilon\alpha\beta}^{\gamma}$ $\Rightarrow \Gamma_{\alpha\beta}^{\gamma} = g^{\gamma\epsilon} \Gamma_{\epsilon\alpha\beta}$ $g \sim$ 度量矩阵

Then $\vec{r}_{\alpha\beta} \cdot \vec{r}_{\epsilon} = \Gamma_{\epsilon\alpha\beta}$

$$\boxed{\Gamma_{\alpha\beta}^{\gamma} = \Gamma_{\beta\alpha}^{\gamma} \quad \Gamma_{\epsilon\alpha\beta}^{\gamma} = \Gamma_{\epsilon\beta\alpha}^{\gamma}}$$

$$g_{\alpha\beta} = \vec{r}_{\alpha} \cdot \vec{r}_{\beta} \Rightarrow \frac{\partial g_{\alpha\beta}}{\partial u^{\gamma}} = \vec{r}_{\alpha\gamma} \cdot \vec{r}_{\beta} + \vec{r}_{\alpha} \cdot \vec{r}_{\beta\gamma} \\ = \Gamma_{\beta\alpha\gamma} + \Gamma_{\alpha\beta\gamma}$$

$$\Rightarrow \begin{cases} \frac{\partial g_{\alpha\beta}}{\partial u^{\gamma}} = \Gamma_{\alpha\beta\gamma} + \Gamma_{\beta\alpha\gamma} \\ \frac{\partial g_{\alpha\beta}}{\partial u^{\alpha}} = \Gamma_{\beta\alpha\alpha} + \Gamma_{\alpha\beta\alpha} \end{cases}$$

$$2T_{\alpha\beta} = \frac{\partial g_{\alpha\gamma}}{\partial u^\beta} + \frac{\partial g_{\gamma\beta}}{\partial u^\alpha} - \frac{\partial g_{\alpha\beta}}{\partial u^\gamma}$$

$$\Rightarrow \Gamma_{\alpha\beta} = \frac{1}{2} \left(\frac{\partial g_{\alpha\gamma}}{\partial u^\beta} + \frac{\partial g_{\gamma\beta}}{\partial u^\alpha} - \frac{\partial g_{\alpha\beta}}{\partial u^\gamma} \right)$$

$$T_{\alpha\beta}^\gamma = \frac{1}{2} g^{\gamma\epsilon} \left(\frac{\partial g_{\alpha\epsilon}}{\partial u^\beta} + \frac{\partial g_{\epsilon\beta}}{\partial u^\alpha} - \frac{\partial g_{\alpha\beta}}{\partial u^\epsilon} \right)$$

↑

Christoffel notation

$$\Rightarrow \begin{cases} \frac{\partial \vec{r}_\alpha}{\partial u^\beta} = T_{\alpha\beta}^\gamma \vec{r}_\gamma + b_{\alpha\beta} \vec{n} \\ \frac{\partial \vec{n}}{\partial u^\beta} = -b_{\beta}^\sigma \vec{r}_\sigma \end{cases}$$

Recalling Frenet equations

Example: $z = f(x, y)$ Christoffel notation

$$\vec{r} = (x, y, f(x, y))$$

$$\text{Sol: } \vec{r}_x = (1, 0, f_x), \quad \vec{r}_y = (0, 1, f_y), \quad \vec{r}_{xx} = (0, 0, f_{xx}) \\ \vec{r}_{xy} = (0, 0, f_{xy}), \quad \vec{r}_{yy} = (0, 0, f_{yy})$$

$$\Rightarrow g_{11} = 1 + f_x^2, \quad g_{12} = f_x f_y, \quad g_{22} = 1 + f_y^2, \quad g = 1 + f_x^2 + f_y^2$$

$$g^{11} = \frac{1 + f_y^2}{1 + f_x^2 + f_y^2}, \quad g^{12} = -\frac{f_x f_y}{1 + f_x^2 + f_y^2}, \quad g^{22} = \frac{1 + f_x^2}{1 + f_x^2 + f_y^2}$$

$$\Rightarrow T_{111}, T_{112}, T_{122}, T_{211}, T_{222}, T_{212} = T_{221} \\ T_{121}$$

$$\Rightarrow T_{11}^1, T_{12}^1 = T_{21}^1, T_{22}^1, T_{11}^2, T_{12}^2 = T_{21}^2, T_{22}^2$$

Thm: Let D_1, D_2 be regular surfaces from $D \subset \mathbb{R}^2$ to \mathbb{R}^3 .

If for $\forall (u^1, u^2) \in D$, S_1 and S_2 have the same first and second fundamental forms. Then S_1 and S_2 differ by a rigid motion.

Sketch of proof:

$$l_1 = \{ \vec{r}_1^{(1)}(u_0), \vec{r}_2^{(1)}(u_0), \vec{n}^{(1)}(u_0) \} \quad l_2 = \{ \vec{r}_1^{(2)}(u_0), \vec{r}_2^{(2)}(u_0), \vec{n}^{(2)}(u_0) \}$$

$$\textcircled{1} \exists \sigma: \sigma(l_1) \rightarrow l_2$$

$$\textcircled{2} f_{\alpha\beta}(u) = (\vec{r}_\alpha^{(1)} - \vec{r}_\alpha^{(2)}) \cdot (\vec{r}_\beta^{(1)} - \vec{r}_\beta^{(2)})$$

$$f_\alpha(u) = (\vec{r}_\alpha^{(1)} - \vec{r}_\alpha^{(2)}) \cdot (\vec{n}^{(1)} - \vec{n}^{(2)})$$

$$f(u) = (n^{(1)} - n^{(2)})^2$$

$$\textcircled{3} \text{ prove: } f_{\alpha\beta}(u) \equiv 0, f_\alpha(u) \equiv 0, f(u) \equiv 0$$

$$f_{\alpha\beta}(u_0) = 0, f_\alpha(u_0) = 0, f(u_0) = 0$$

$$\left\{ \begin{array}{l} \frac{\partial f_{\alpha\beta}}{\partial u^r} = \dots \\ \frac{\partial f_\alpha}{\partial u^r} = \dots \\ \frac{\partial f}{\partial u^r} = \dots \end{array} \right.$$

First order.

⑫ Compatibility : Gauss-Codazzi equation.

? Given $\mathcal{G} = g_{\alpha\beta} du^\alpha du^\beta$ $\mathcal{Y} = b_{\alpha\beta} du^\alpha du^\beta$ is there a regular surface in \mathbb{R}^3 : $f: D \rightarrow \mathbb{R}^3$ s.t. \mathcal{G} , \mathcal{Y} are the first and second fundamental forms?

\Rightarrow compatibility equation.

$\{\vec{r}_1, \vec{r}_2, \vec{n}\}$ natural coordinates

$$\begin{cases} \frac{\partial \vec{r}}{\partial u^\alpha} = \vec{r}_\alpha \\ \frac{\partial \vec{r}_\alpha}{\partial u^\beta} = \Gamma_{\alpha\beta}^\gamma \vec{r}_\gamma + b_{\alpha\beta} \vec{n} \\ \frac{\partial \vec{n}}{\partial u^\beta} = -b_\beta^\alpha \vec{r}_\alpha \end{cases} \quad \text{where } \Gamma_{\alpha\beta}^\gamma = \frac{1}{2} g^{\gamma\delta} \left(\frac{\partial g_{\alpha\delta}}{\partial u^\beta} + \frac{\partial g_{\beta\delta}}{\partial u^\alpha} - \frac{\partial g_{\alpha\beta}}{\partial u^\delta} \right)$$

$$b_\beta^\alpha = g^{\alpha\gamma} b_{\gamma\beta}$$

Regular surfaces: $\frac{\partial^2 \vec{r}_\alpha}{\partial u^\beta \partial u^\gamma} = \frac{\partial^2 \vec{r}_\alpha}{\partial u^\gamma \partial u^\beta}$, $\frac{\partial^2 \vec{n}}{\partial u^\beta \partial u^\gamma} = \frac{\partial^2 \vec{n}}{\partial u^\gamma \partial u^\beta}$

$$\begin{cases} \frac{\partial}{\partial u^\gamma} (\Gamma_{\alpha\beta}^\delta \vec{r}_\delta + b_{\alpha\beta} \vec{n}) = \frac{\partial}{\partial u^\beta} (\Gamma_{\alpha\gamma}^\delta \vec{r}_\delta + b_{\alpha\gamma} \vec{n}) \\ \frac{\partial}{\partial u^\gamma} (b_\beta^\delta \vec{r}_\delta) = \frac{\partial}{\partial u^\beta} (b_\gamma^\delta \vec{r}_\delta) \end{cases}$$

$$\Rightarrow \frac{\partial}{\partial u^\gamma} \Gamma_{\alpha\beta}^\delta - \frac{\partial}{\partial u^\beta} \Gamma_{\alpha\gamma}^\delta + \Gamma_{\alpha\beta}^\eta \Gamma_{\eta\gamma}^\delta - \Gamma_{\alpha\gamma}^\eta \Gamma_{\eta\beta}^\delta - b_{\alpha\beta} b_\gamma^\delta + b_{\alpha\gamma} b_\beta^\delta) \vec{r}_\delta$$

$$+ (\Gamma_{\alpha\beta}^\delta b_{\gamma\delta} - \Gamma_{\alpha\gamma}^\delta b_{\beta\delta} + \frac{\partial b_{\alpha\beta}}{\partial u^\gamma} - \frac{\partial b_{\alpha\gamma}}{\partial u^\beta}) \vec{n} = 0$$

$$\Rightarrow \begin{cases} \frac{\partial}{\partial u^\gamma} \Gamma_{\alpha\beta}^\delta - \frac{\partial}{\partial u^\beta} \Gamma_{\alpha\gamma}^\delta + \Gamma_{\alpha\beta}^\eta \Gamma_{\eta\gamma}^\delta - \Gamma_{\alpha\gamma}^\eta \Gamma_{\eta\beta}^\delta = b_{\alpha\beta} b_\gamma^\delta - b_{\alpha\gamma} b_\beta^\delta \\ \frac{\partial b_{\alpha\beta}}{\partial u^\gamma} - \frac{\partial b_{\alpha\gamma}}{\partial u^\beta} = \Gamma_{\alpha\gamma}^\delta b_{\beta\delta} - \Gamma_{\alpha\beta}^\delta b_{\gamma\delta} \end{cases}$$

Riemann notation: $R^\sigma_{\alpha\beta\gamma} = \frac{\partial}{\partial u^\alpha} \Gamma^\sigma_{\beta\gamma} - \frac{\partial}{\partial u^\beta} \Gamma^\sigma_{\alpha\gamma} + \Gamma^\sigma_{\alpha\beta} \Gamma^\delta_{\gamma\delta} - \Gamma^\sigma_{\alpha\gamma} \Gamma^\delta_{\beta\delta}$

$$R_{\alpha\beta\gamma\delta} = g_{\delta\eta} R^\eta_{\alpha\beta\gamma}, \quad R^\delta_{\alpha\beta\gamma} = g^{\delta\eta} R_{\alpha\eta\beta\gamma}$$

$$\Rightarrow R^\delta_{\alpha\beta\gamma} = b_{\alpha\beta} b^\delta_\gamma - b_{\alpha\gamma} b^\delta_\beta$$

or $R_{\alpha\beta\gamma\delta} = b_{\alpha\beta} b_{\gamma\delta} - b_{\alpha\gamma} b_{\beta\delta}$ — Gauss equation

$$\frac{\partial b_{\alpha\beta}}{\partial u^\alpha} - \frac{\partial b_{\alpha\gamma}}{\partial u^\beta} = \Gamma^\delta_{\alpha\gamma} b_{\beta\delta} - \Gamma^\delta_{\alpha\beta} b_{\gamma\delta} \quad \text{— Codazzi equation}$$

1 equation in Gauss:

$$R_{\alpha\beta\gamma\delta} = g_{\delta\eta} \left(\frac{\partial}{\partial u^\alpha} \Gamma^\eta_{\beta\gamma} - \frac{\partial}{\partial u^\beta} \Gamma^\eta_{\alpha\gamma} + \Gamma^\xi_{\alpha\beta} \Gamma^\eta_{\gamma\xi} - \Gamma^\xi_{\alpha\gamma} \Gamma^\eta_{\beta\xi} \right)$$

$$= \frac{\partial \Gamma_{\alpha\beta\gamma}}{\partial u^\alpha} - \frac{\partial \Gamma_{\alpha\gamma\beta}}{\partial u^\beta} - \frac{\partial g_{\delta\eta}}{\partial u^\alpha} \Gamma^\eta_{\beta\gamma} + \frac{\partial g_{\delta\eta}}{\partial u^\beta} \Gamma^\eta_{\alpha\gamma} + \Gamma^\xi_{\alpha\beta} \Gamma_{\gamma\xi\delta} - \Gamma^\xi_{\alpha\gamma} \Gamma_{\beta\xi\delta}$$

$$= \frac{\partial \Gamma_{\alpha\beta\gamma}}{\partial u^\alpha} - \frac{\partial \Gamma_{\alpha\gamma\beta}}{\partial u^\beta} + \Gamma_{\eta\delta\beta} \Gamma^\eta_{\alpha\gamma} - \Gamma_{\eta\delta\alpha} \Gamma^\eta_{\beta\gamma}$$

$$R_{\alpha\beta\gamma\delta} = \frac{1}{2} \left(\frac{\partial^2 g_{\delta\beta}}{\partial u^\alpha \partial u^\alpha} + \frac{\partial^2 g_{\alpha\gamma}}{\partial u^\delta \partial u^\beta} - \frac{\partial^2 g_{\delta\gamma}}{\partial u^\alpha \partial u^\beta} - \frac{\partial^2 g_{\alpha\beta}}{\partial u^\delta \partial u^\alpha} \right)$$

$$+ \Gamma_{\eta\delta\beta} \Gamma^\eta_{\alpha\gamma} - \Gamma_{\eta\delta\alpha} \Gamma^\eta_{\beta\gamma}$$

$$\Rightarrow R_{\alpha\beta\gamma\delta} = R_{\beta\gamma\alpha\delta} = -R_{\delta\alpha\beta\gamma} = -R_{\alpha\delta\beta\gamma}$$

$$\Rightarrow R_{1212} = b_{11} b_{22} - (b_{12})^2 \quad \sim \text{Gauss}$$

\Rightarrow Gauss Theorema ~~Egregium~~ Egregium

2 equations in Codazzi.

$$\left\{ \begin{array}{l} \frac{\partial b_{11}}{\partial u^2} - \frac{\partial b_{12}}{\partial u^1} = -b_{2\delta} \Gamma_{11}^{\delta} + b_{1\delta} \Gamma_{12}^{\delta} \\ \frac{\partial b_{21}}{\partial u^2} - \frac{\partial b_{22}}{\partial u^1} = -b_{2\delta} \Gamma_{21}^{\delta} + b_{1\delta} \Gamma_{22}^{\delta} \end{array} \right.$$