

Date

Compatibility, Fundamental theorem, Gauss's Theorema Egregium, geodesic curvature (Liouville equation), Gauss-Bonnet Theorem.

(12) Compatibility: Gauss-Codazzi equation.

- regular surface:  $\vec{r} = \vec{r}(u, v)$ , or  $\vec{r} = \vec{r}(u^1, u^2)$
- natural coordinates:  $\{\vec{r}_u, \vec{r}_v, \vec{n}\}$  where  $\vec{n} = \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|}$
- or  $\{\vec{r}_1, \vec{r}_2, \vec{n}\}$ ,  $\vec{r} = \vec{r}(u^1, u^2)$

motion of natural coordinates:

$$\begin{cases} \frac{\partial \vec{r}_\alpha}{\partial u^\beta} = \Gamma_{\alpha\beta}^\gamma \vec{r}_\gamma + b_{\alpha\beta} \vec{n} \\ \frac{\partial \vec{n}}{\partial u^\beta} = -b_{\beta\gamma}^\gamma \vec{r}_\gamma \end{cases}$$

$$g_{\alpha\beta} = \vec{r}_\alpha \cdot \vec{r}_\beta, \quad g^{\alpha\beta} g_{\beta\gamma} = \delta_\gamma^\alpha$$

$$b_{\alpha\beta} = \vec{r}_{\alpha\beta} \cdot \vec{n} = -\vec{r}_\alpha \cdot \vec{n}_\beta$$

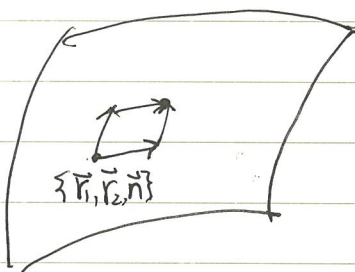
$$b_{\beta\gamma}^\alpha = b_{\beta\gamma} g^{\alpha\gamma}$$

$$b_{\beta\gamma}^\eta = b_{\beta\gamma} g^{\eta\gamma}$$

$$\Gamma_{\alpha\beta}^\gamma = \frac{1}{2} g^{\gamma\delta} \left( \frac{\partial g_{\alpha\delta}}{\partial u^\beta} + \frac{\partial g_{\beta\delta}}{\partial u^\alpha} - \frac{\partial g_{\alpha\beta}}{\partial u^\delta} \right)$$

Christoffel notation.

• Compatibility



$$\frac{\partial^2 \vec{r}_\alpha}{\partial u^\beta \partial u^\gamma} = \frac{\partial^2 \vec{r}_\alpha}{\partial u^\gamma \partial u^\beta}, \quad \frac{\partial^2 \vec{n}}{\partial u^\beta \partial u^\gamma} = \frac{\partial^2 \vec{n}}{\partial u^\gamma \partial u^\beta} \quad \Rightarrow$$

Gauss equation:  $R_{\alpha\beta\gamma}^\delta = b_{\alpha\beta} b_{\gamma}^\delta - b_{\alpha\gamma} b_{\beta}^\delta$  or  $R_{\alpha\beta\gamma}^\delta = b_{\alpha\beta} b_{\gamma}^\delta - b_{\alpha\gamma} b_{\beta}^\delta$

where  $R_{\alpha\beta\gamma}^\delta = g^{\delta\eta} R_{\alpha\beta\gamma}^\eta$

$$R_{\alpha\beta\gamma}^\delta = \frac{\partial}{\partial u^\gamma} \Gamma_{\alpha\beta}^\delta - \frac{\partial}{\partial u^\beta} \Gamma_{\alpha\gamma}^\delta + \Gamma_{\alpha\beta}^\eta \Gamma_{\eta\gamma}^\delta - \Gamma_{\alpha\gamma}^\eta \Gamma_{\eta\beta}^\delta$$

Codazzi equation:  $\frac{\partial b_{\alpha\beta}}{\partial u^\alpha} - \frac{\partial b_{\alpha\gamma}}{\partial u^\beta} = \Gamma_{\alpha\gamma}^\delta b_{\delta\beta} - \Gamma_{\alpha\beta}^\delta b_{\delta\gamma}$

Next ...

Riemann notation:  $R_{\alpha\beta\gamma\delta} = \frac{1}{2} \left( \frac{\partial^2 g_{\delta\beta}}{\partial u^\alpha \partial u^\gamma} + \frac{\partial^2 g_{\alpha\gamma}}{\partial u^\delta \partial u^\beta} - \frac{\partial^2 g_{\delta\gamma}}{\partial u^\alpha \partial u^\beta} - \frac{\partial^2 g_{\alpha\beta}}{\partial u^\delta \partial u^\gamma} \right) + \Gamma_{\gamma\delta\beta}^\eta \Gamma_{\alpha\gamma}^\eta - \Gamma_{\gamma\delta\gamma}^\eta \Gamma_{\alpha\beta}^\eta$

$\Rightarrow R_{\alpha\beta\gamma\delta} = R_{\beta\gamma\alpha\delta} = -R_{\delta\alpha\beta\gamma} = -R_{\alpha\delta\gamma\beta}$

$\Rightarrow$  Gauss equation:  $R_{1212} = b_{11}b_{22} - (b_{12})^2$

Codazzi equation:

$$\left\{ \begin{array}{l} \frac{\partial b_{11}}{\partial u^2} - \frac{\partial b_{12}}{\partial u^1} = -b_{22}\Gamma_{11}^\delta + b_{1\delta}\Gamma_{12}^\delta \\ \frac{\partial b_{21}}{\partial u^2} - \frac{\partial b_{22}}{\partial u^1} = -b_{2\delta}\Gamma_{21}^\delta + b_{1\delta}\Gamma_{22}^\delta \end{array} \right. \quad (*)$$

• 正交曲线参数网 ( $\vec{F}_u \cdot \vec{F}_v = 0$ ): Gauss:  $R_{1212} = -\sqrt{EG} \left[ \left( \frac{\sqrt{E}}{\sqrt{G}} \right)_v + \left( \frac{\sqrt{G}}{\sqrt{E}} \right)_u \right]$   
orthogonal parameterization

• 正交曲率线网



curve along the principal direction, where  $H = \frac{1}{2} \left( \frac{L}{E} + \frac{N}{G} \right)$

Codazzi:  $\frac{\partial L}{\partial v} = H \frac{\partial E}{\partial v}, \frac{\partial N}{\partial u} = H \frac{\partial G}{\partial u}$

## (13) Fundamental theorem

$D \subset \mathbb{R}^2$  is connected. Let  $\varphi = g_{\alpha\beta} du^\alpha du^\beta$ ,  $\psi = b_{\alpha\beta} du^\alpha du^\beta$  be two differential forms.  $g_{\alpha\beta}$   $b_{\alpha\beta}$  differentiable,  $g_{\alpha\beta} = g_{\beta\alpha}$ ,  $b_{\alpha\beta} = b_{\beta\alpha}$ ,  $g_{\alpha\beta}$  positive definite.

$$\Gamma_{\alpha\beta}^\gamma = \frac{1}{2} \left( \frac{\partial g_{\alpha\beta}}{\partial u^\gamma} + \frac{\partial g_{\alpha\gamma}}{\partial u^\beta} - \frac{\partial g_{\beta\gamma}}{\partial u^\alpha} \right), \quad \Gamma_{\alpha\beta}^\gamma = g^{\delta\sigma} \Gamma_{\sigma\alpha\beta}^\gamma$$

$$R_{\alpha\beta\gamma}^\delta = \frac{\partial \Gamma_{\alpha\beta}^\delta}{\partial u^\gamma} - \frac{\partial \Gamma_{\alpha\gamma}^\delta}{\partial u^\beta} + \Gamma_{\alpha\beta}^\eta \Gamma_{\eta\gamma}^\delta - \Gamma_{\alpha\gamma}^\eta \Gamma_{\eta\beta}^\delta, \quad R_{\alpha\beta\gamma\delta} = g_{\delta\eta} R_{\alpha\beta\gamma}^\eta$$

Thm. If  $\varphi, \psi$  satisfy the Gauss-Codazzi equations (\*) then for  $\forall (u^1, u^2) \in D$   $\exists$  its neighborhood  $U \subset D$  and a regular surface  $S: \vec{r} = \vec{r}(u^1, u^2)$ ,  $(u^1, u^2) \in U$  s.t. the first and second fundamental forms of  $S$  are  $\varphi|_U$  and  $\psi|_U$ . Furthermore, any two surfaces satisfying the above conditions differ by a rigid motion.

proof: Uniqueness. proved. ①  $\sigma(\vec{r}_1^{(2)}(u_0), \vec{r}_2^{(2)}(u_0), \vec{n}^{(2)}(u_0)) = (\vec{r}_1^{(1)}(u_0), \vec{r}_2^{(1)}(u_0), \vec{n}^{(1)}(u_0))$   
 $u_0 = (u_0^1, u_0^2)$

$$\textcircled{2} f_{\alpha\beta}(u) = (\vec{r}_\alpha^{(1)} - \vec{r}_\alpha^{(2)}) \cdot (\vec{r}_\beta^{(1)} - \vec{r}_\beta^{(2)})$$

$$f_\alpha(u) = (\vec{r}_\alpha^{(1)} - \vec{r}_\alpha^{(2)}) \cdot (\vec{n}^{(1)} - \vec{n}^{(2)})$$

$$f(u) = (\vec{n}^{(1)} - \vec{n}^{(2)})^2$$

$$\textcircled{3} f_{\alpha\beta}(u_0) = f_\alpha(u_0) = f(u_0) = 0.$$

$$\Rightarrow f_{\alpha\beta}(u) \equiv 0, f_\alpha(u) \equiv 0, f(u) \equiv 0$$

$$\text{by } \frac{\partial f_{\alpha\beta}}{\partial u^\gamma} = \dots = \frac{\partial f_\alpha}{\partial u^\gamma} = \dots = \frac{\partial f}{\partial u^\gamma} = \dots$$

Existence:

① Construct the 1st order PDE system

$$\frac{\partial \vec{r}}{\partial u^\beta} = \vec{r}_\beta$$

$$\frac{\partial \vec{n}}{\partial u^\beta} = -b_\beta^\gamma \vec{r}_\gamma$$

$$\frac{\partial \vec{r}_\alpha}{\partial u^\beta} = \Gamma_{\alpha\beta}^\gamma \vec{r}_\gamma + b_{\alpha\beta} \vec{n}$$

$\vec{F}, \vec{r}_1, \vec{r}_2, \vec{n}$  unknown,  $u^1, u^2$  variables.

② Existence of solution to first-order PDE systems. (陈附录1)

$$\frac{\partial}{\partial u^\alpha} \left( \frac{\partial \vec{F}}{\partial u^\beta} \right) = \frac{\partial}{\partial u^\beta} \left( \frac{\partial \vec{F}}{\partial u^\alpha} \right), \quad \frac{\partial}{\partial u^\alpha} \left( \frac{\partial \vec{r}_2}{\partial u^\beta} \right) = \frac{\partial}{\partial u^\beta} \left( \frac{\partial \vec{r}_2}{\partial u^\alpha} \right)$$

$$\frac{\partial}{\partial u^\alpha} \left( \frac{\partial \vec{n}}{\partial u^\beta} \right) = \frac{\partial}{\partial u^\beta} \left( \frac{\partial \vec{n}}{\partial u^\alpha} \right)$$

$\Rightarrow$  for  $\forall$  initial values  $\vec{F}^0, \vec{r}_1^0, \vec{r}_2^0, \vec{n}^0 \exists \vec{F}, \vec{r}_1, \vec{r}_2, \vec{n}$  in a neighborhood.

③ Choose  $\{\vec{F}^0, \vec{r}_1^0, \vec{r}_2^0, \vec{n}^0\}$  s.t.

$$\begin{aligned} \vec{r}_\alpha^0 \cdot \vec{r}_\beta^0 &= g_{\alpha\beta}(u^0, u^2) \\ \vec{r}_\alpha^0 \cdot \vec{n}^0 &= 0 \\ \vec{n}^0 \cdot \vec{n}^0 &= 1 \\ (\vec{r}_1^0, \vec{r}_2^0, \vec{n}^0) &> 0 \end{aligned}$$

Consider  $f_{\alpha\beta} = \vec{r}_\alpha \cdot \vec{r}_\beta - g_{\alpha\beta}$   
 $f_\alpha = \vec{r}_\alpha \cdot \vec{n}$   
 $f = \vec{n} \cdot \vec{n} - 1$

use  $\begin{cases} \frac{\partial f_{\alpha\beta}}{\partial u^\alpha} = \dots \\ \frac{\partial f_\alpha}{\partial u^\alpha} = \dots \\ \frac{\partial f}{\partial u^\alpha} = \dots \end{cases}$  and  $f_{\alpha\beta}(u^0) = f_\alpha(u^0) = f(u^0) = 0$

$\Rightarrow f_{\alpha\beta} \equiv 0, f_\alpha \equiv 0, f \equiv 0$

$\Rightarrow (\vec{r}_1, \vec{r}_2, \vec{n})^2 = \det(g_{\alpha\beta}) > 0$   
 $\therefore$  continuity  $\Rightarrow (\vec{r}_1, \vec{r}_2, \vec{n}) > 0$

④  $\vec{F} = \vec{F}(u^1, u^2)$  is a regular surface with  $\mathcal{G}, \mathcal{F}$  being the first and second fundamental forms.

⑭ Gauss's Theorema Egregium. (Remarkable Thm)

Gauss equation:  $b_{11}b_{22} - (b_{12})^2 = R_{1212}$

$$K = \frac{b_{11}b_{22} - (b_{12})^2}{g_{11}g_{22} - (g_{12})^2} = \frac{R_{1212}}{g_{11}g_{22} - (g_{12})^2}$$

↑ only depends on the first fundamental form

Theorema Egregium: The Gauss curvature  $K$  of a surface is invariant by local isometries.

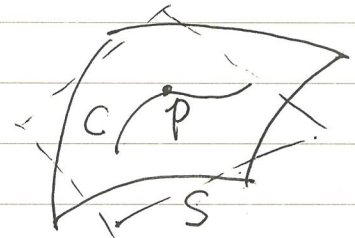
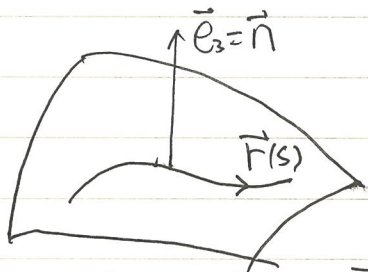
Orthogonal parameterization: 
$$K = -\frac{1}{\sqrt{EG}} \left[ \left( \frac{\sqrt{E}}{\sqrt{G}} \right)_v + \left( \frac{\sqrt{G}}{\sqrt{E}} \right)_u \right]$$

Thm 14.1: 无脐点 (umbilical point) surface is developal  $\Leftrightarrow K=0$

Example: Spherical surface and cylindrical surface.

⑮ Geodesic curvature 测地曲率 and Liouville equation.

Geodesic curvature: curvature of a curve projected on the tangent plane



Frenet frame  $\{\vec{\alpha}(s), \vec{\beta}(s), \vec{\gamma}(s)\}$

$$\vec{\alpha}(s) = \vec{r}'(s)$$

$$\vec{\alpha}'(s) = \kappa(s) \vec{\beta}(s)$$

$$\vec{\gamma}(s) = \vec{\alpha}(s) \times \vec{\beta}(s)$$

Frenet equation:

$$\begin{pmatrix} \vec{\alpha}'(s) \\ \vec{\beta}'(s) \\ \vec{\gamma}'(s) \end{pmatrix} = \begin{pmatrix} 0 & \kappa(s) & 0 \\ -\kappa(s) & 0 & \tau(s) \\ 0 & -\tau(s) & 0 \end{pmatrix} \begin{pmatrix} \vec{\alpha}(s) \\ \vec{\beta}(s) \\ \vec{\gamma}(s) \end{pmatrix}$$

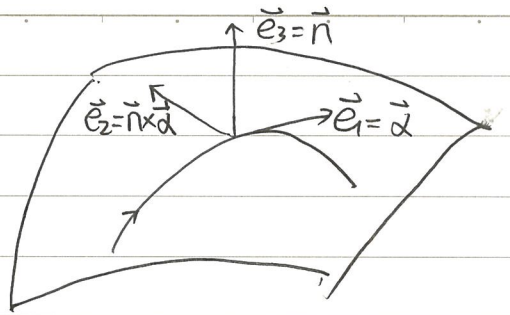
Date

Darboux frame  $\{\vec{e}_1, \vec{e}_2, \vec{e}_3\}$

$$\vec{e}_1 = \vec{\alpha}(s)$$

$$\vec{e}_3 = \vec{n}(s)$$

$$\vec{e}_2 = \vec{e}_3 \times \vec{e}_1 = \vec{n}(s) \times \vec{\alpha}(s)$$



Darboux formula:

$$\begin{pmatrix} \vec{e}_1'(s) \\ \vec{e}_2'(s) \\ \vec{e}_3'(s) \end{pmatrix} = \begin{pmatrix} 0 & k_g & k_n \\ -k_g & 0 & \tau_g \\ -k_n & -\tau_g & 0 \end{pmatrix} \begin{pmatrix} \vec{e}_1 \\ \vec{e}_2 \\ \vec{e}_3 \end{pmatrix}$$

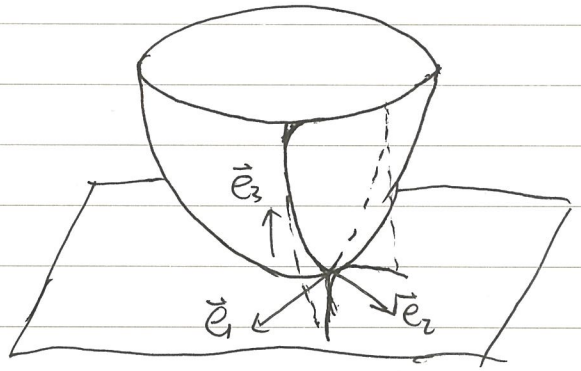
$k_n = \vec{r}''(s) \cdot \vec{n} \sim$  normal curvature.

$k_g = \vec{r}''(s) \cdot (\vec{n}(s) \times \vec{r}'(s)) = (\vec{n}(s), \vec{r}'(s), \vec{r}''(s)) \sim$  geodesic curvature.

$\tau_g = \vec{e}_2'(s) \cdot \vec{n}(s) = \frac{d}{ds} (\vec{n} \times \vec{r}'(s)) \cdot \vec{n} = (\vec{n}(s), \vec{n}'(s), \vec{r}''(s)) \sim$  geodesic torsion.

$$k_g = \vec{n} \cdot (\vec{\alpha}(s) \times (k \vec{\beta}(s))) = k \vec{n} \cdot \vec{f}(s)$$

$$\Rightarrow \boxed{k \vec{\beta}(s) = k_g \vec{e}_2 + k_n \vec{n}}$$



Thm:  $k_g$  is intrinsic  $\sim k_g$  is invariant under isometries.

proof:  $S: \vec{r} = \vec{r}(u^1, u^2)$ , curve  $C: u^1 = u^1(s), u^2 = u^2(s)$   
 $\vec{r}(s) = \vec{r}(u^1(s), u^2(s))$

$$\vec{e}_1(s) = \vec{\alpha}(s) = \vec{r}_\alpha \frac{du^\alpha(s)}{ds}$$

$$\frac{d\vec{e}_1(s)}{ds} = \vec{r}_{\alpha\beta} \frac{du^\alpha(s)}{ds} \frac{du^\beta(s)}{ds} + \vec{r}_\alpha \frac{d^2 u^\alpha(s)}{ds^2}$$

$$= \left( \frac{d^2 u^\alpha(s)}{ds^2} + \Gamma_{\alpha\beta}^\gamma \frac{du^\alpha(s)}{ds} \frac{du^\beta(s)}{ds} \right) \vec{r}_\gamma + b_{\alpha\beta} \frac{du^\alpha(s)}{ds} \frac{du^\beta(s)}{ds} \vec{n}$$

$$k_g = \frac{d\vec{e}_1(s)}{ds} \cdot \vec{e}_2(s)$$

⋮

$$k_g = |\vec{r}_1 \times \vec{r}_2| \left[ \frac{du^1}{ds} \left( \frac{d^2u^2}{ds^2} + \Gamma_{\alpha\beta}^2 \frac{du^\alpha}{ds} \frac{du^\beta}{ds} \right) - \frac{du^2}{ds} \left( \frac{d^2u^1}{ds^2} + \Gamma_{\alpha\beta}^1 \frac{du^\alpha}{ds} \frac{du^\beta}{ds} \right) \right]$$

$$= \sqrt{g_{11}g_{22} - (g_{12})^2} \begin{vmatrix} \frac{du^1}{ds} & \frac{d^2u^1}{ds^2} + \Gamma_{\alpha\beta}^1 \frac{du^\alpha}{ds} \frac{du^\beta}{ds} \\ \frac{du^2}{ds} & \frac{d^2u^2}{ds^2} + \Gamma_{\alpha\beta}^2 \frac{du^\alpha}{ds} \frac{du^\beta}{ds} \end{vmatrix}$$

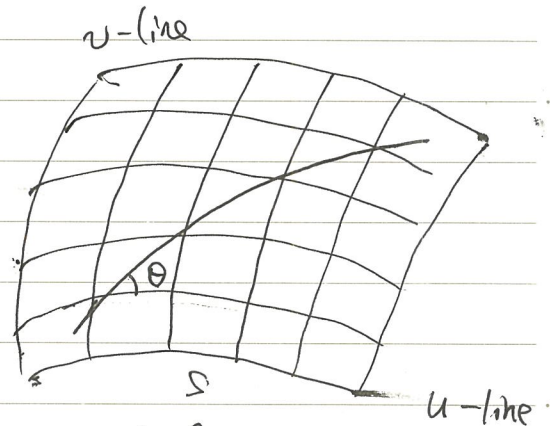
~ Intrinsic!

Liouville formula

(u, v) orthogonal coordinates

$$S: I = E(du)^2 + G(dv)^2$$

$$C: u = u(s), v = v(s)$$



$$k_g \text{ of } C: k_g = \frac{d\theta}{ds} - \frac{1}{2\sqrt{G}} \frac{\partial \log E}{\partial v} \cos\theta + \frac{1}{2\sqrt{E}} \frac{\partial \log G}{\partial u} \sin\theta$$

$$\text{HW 3: } = \frac{d\theta}{ds} + \frac{1}{2\sqrt{EG}} \left[ G_u \frac{dv}{ds} - E_v \frac{du}{ds} \right]$$

- $\tau_g$  geodesic torsion is NOT intrinsic.  $\tau_g = (\vec{n}(s), \vec{n}'(s), \vec{r}'(s))$

## (16) The Gauss-Bonnet Theorem.

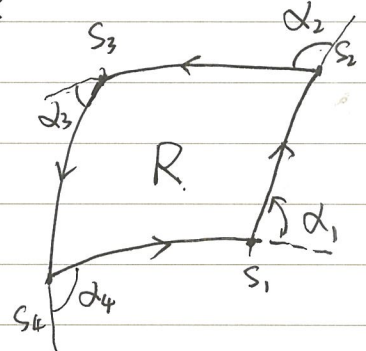
(Local) Gauss-Bonnet Theorem:

Let  $S: \vec{r}(u,v)$  be an orthogonal parameterized surface.

$R \subset \vec{r}(u)$  is a simple region of  $S$ , ~~if~~

Then 
$$\oint_{\partial R} kg \, ds + \iint_R k \, d\sigma = 2\pi - \sum_{i=1}^n \alpha_i$$

$\alpha_i$  is the external angle.



proof: 
$$\oint_{\partial R} kg \, ds = \sum_{i=0}^n \int_{S_i}^{S_{i+1}} kg(s) \, ds.$$

$$kg(s) = \frac{1}{2\sqrt{EG}} \left[ G_u \frac{dv}{ds} - E_v \frac{du}{ds} \right] + \frac{d\theta_i}{ds}, \quad \theta_i \text{ is the angle from } \vec{r}_u \text{ to } \partial R(s)$$

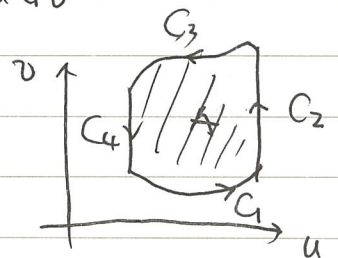
$$\sum_{i=0}^n \int_{S_i}^{S_{i+1}} kg(s) \, ds = \sum_{i=0}^n \int_{S_i}^{S_{i+1}} \left( \frac{G_u}{2\sqrt{EG}} \frac{dv}{ds} - \frac{E_v}{2\sqrt{EG}} \frac{du}{ds} \right) ds + \sum_{i=0}^n \int_{S_i}^{S_{i+1}} \frac{d\theta_i}{ds} ds$$

Gauss-Green Theorem: If  $P(u,v), Q(u,v)$  are differentiable functions in a simple domain  $A \subset \mathbb{R}^2$ , the boundary of which is  $u=u(s), v=v(s)$

Then 
$$\sum_{i=1}^n \int_{S_i}^{S_{i+1}} \left( P \frac{du}{ds} + Q \frac{dv}{ds} \right) ds = \iint_A \left( \frac{\partial Q}{\partial u} - \frac{\partial P}{\partial v} \right) du \, dv$$

$$\oint P \, du = \iint_A \left( -\frac{\partial P}{\partial v} \right) dA, \quad \oint Q \, dv = \iint_A \frac{\partial Q}{\partial u} dA$$

or 
$$\oint \vec{F} \cdot d\vec{r} = \iint \nabla \times \vec{F} \cdot \hat{n} \, dA$$



$$\Rightarrow \sum_{i=0}^n \int_{S_i}^{S_{i+1}} kg(s) \, ds = \iint \left[ \left( \frac{E_v}{2\sqrt{EG}} \right)_v + \left( \frac{G_u}{2\sqrt{EG}} \right)_u \right] du \, dv + \sum_{i=0}^n \int_{S_i}^{S_{i+1}} \frac{d\theta_i}{ds} ds$$



$$\iint_{F^{-1}(R)} \left[ \left( \frac{E_v}{2\sqrt{EG}} \right)_v + \left( \frac{G_u}{2\sqrt{EG}} \right)_u \right] dudv = - \iint_{F^{-1}(R)} K \sqrt{EG} dudv = - \iint_R K d\sigma$$

↑

for orthogonal parameterization,  $K = -\frac{1}{\sqrt{EG}} \left[ \left( \frac{\sqrt{E}}{\sqrt{G}} \right)_v + \left( \frac{\sqrt{G}}{\sqrt{E}} \right)_u \right]$

$$\sum_{i=0}^n \int_{s_i}^{s_{i+1}} \frac{d\theta}{ds} ds = 2\pi - \sum_{i=0}^n \alpha_i$$

$$\Rightarrow \sum_{i=0}^n \int_{s_i}^{s_{i+1}} K g(s) ds + \iint_R K d\sigma \neq \sum_{i=0}^n \alpha_i = 2\pi \quad \text{Q.E.D.}$$

$$\text{or } \oint_{\partial R} K g ds + \iint_R K d\sigma = 2\pi - \sum_{i=1}^n \alpha_i$$

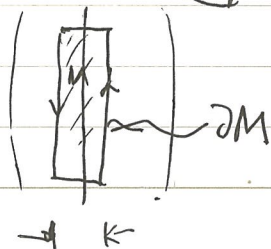
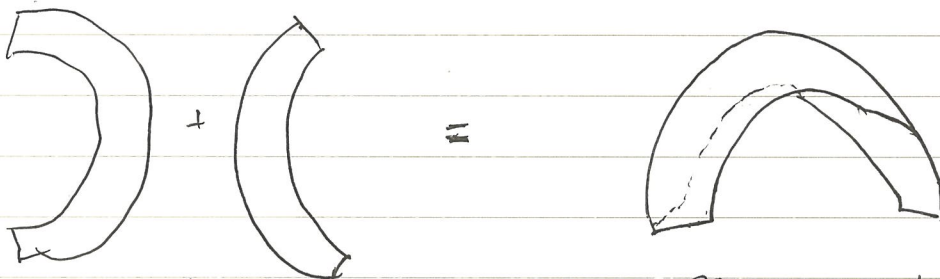
(Global) Gauss-Bonnet Theorem.

Let  $R \subset S$  be a regular region of an oriented surface and let  $C_1, \dots, C_n$  be the closed, simple, piecewise regular curves which form  $\partial R$ .

Suppose each  $C_i$  is positively oriented and let  $\theta_1, \dots, \theta_p$  be the external angles of  $C_1, \dots, C_n$ . Then

$$\sum_{i=1}^n \int_{C_i} K g(s) ds + \iint_R K d\sigma + \sum_{i=1}^p \theta_i = 2\pi \chi(R)$$

Example: intrinsically curved folds



$$\Omega = \iint_M K ds, \quad \frac{d\Omega}{ds} = K g_1 - K g_2$$